# On Jachymski's theorem 

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Abstract. In this note we prove that a fixed point theorem (due to Jachymski in [5]) extends
and subsumes some results in the fixed point theory.
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## 1. Introduction

The classical Banachs contraction principle is one of the most useful results in fixed point theory. In a metric space setting it can be briefly stated as follows.

Theorem 1.1. Let $(X, d)$ be a complete metric space and $T: X \rightarrow X$ a strict contraction, i.e. a map satisfying

$$
\begin{equation*}
d(T x, T y) \leqslant a d(x, y), \text { for all } x, y \in X, \tag{1}
\end{equation*}
$$

where $0<a<1$ is constant. Then:
(1) $T$ has a unique fixed point $x^{*}$ in $X$;
(2) The Picard iteration $\left(x_{n}\right)_{n \geqslant 0}$ defined by

$$
\begin{equation*}
x_{n+1}=T x_{n}, n=0,1,2, \ldots \tag{2}
\end{equation*}
$$

converges to $x^{*}$, for any $x_{0} \in X$.
There is more than one way to generalize the Banach's contraction mapping principle. One of them is to get the subset $M$ of $X \times X$, the contraction condition to be satisfied only for $(x, y) \in M$ and still the operator is the operator is a Picard operator (abbr. PO). This article will prove that the Jachymski's theorem is one of the most general theorems of its kind.

Let $T$ be a selfmap of a metric space $(X, d)$. Following Petruşel and Rus [12], we say that $T$ is a Picard operator if $T$ has a unique fixed point $x^{*}$ and $\lim _{n \rightarrow \infty} T^{n} x=x^{*}$ for all $x \in X$ and $T$ is a weakly Picard operator (abbr. WPO) if the sequence $\left(T^{n} x\right)_{n \in \mathbb{N}}$ converges, for all $x \in X$ and the limit (which may depend on $x$ ) is a fixed point of $T$. Thus any contraction on complete metric space is PO.

Let $(X, d)$ be a metric space. Let $\Delta$ denote the diagonal of the Cartesian product $X \times X$. Consider a directed graph $G$ such that the set $V(G)$ of its vertices coincides with $X$, and the set $E(G)$ of its edges contains all loops, i.e., $E(G) \supseteq \Delta$. We assume $G$ has no parallel edges, so we can identify $G$ with the pair $(V(G), E(G))$. Moreover, we may treat $G$ as a weighted graph (see [[6], p. 309]) by assigning to each edge the

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distance between its vertices. By $G^{-1}$ we denote the conversion of graph $G$, i.e. the graph obtained from $G$ by reversing the direction of edges. Thus we have

$$
E\left(G^{-1}\right)=\{(x, y) \mid(y, x) \in G\}
$$

The letter $\tilde{G}$ denotes the undirected graph obtained from $G$ by ignoring the direction of edges. Actually, it will be more convenient for us to treat $\tilde{G}$ as a directed graph for which the set of its edges is symmetric. Under this convention,

$$
\begin{equation*}
E(\tilde{G})=E(G) \cup E\left(G^{-1}\right) \tag{3}
\end{equation*}
$$

We call $\left(V^{\prime}, E^{\prime}\right)$ a subgraph of $G$ if $V^{\prime} \subseteq V(G), E^{\prime} \subseteq E(G)$ and for any edge $(x, y) \in E^{\prime}, x, y \in V^{\prime}$.

Now we recall a few basic notions concerning the connectivity of graphs. All of them can be found, e.g., in [6]. If $x$ and $y$ are vertices in a graph $G$, then a path in $G$ from $x$ to $y$ of length $N(N \in \mathbb{N})$ is a sequence $\left(x_{i}\right)_{i=0}^{N}$ of $N+1$ vertices such that $x_{0}=x, x_{N}=y$ and $\left(x_{i-1}, x_{i}\right) \in E(G)$ for $i=1, \ldots, N$. A graph $G$ is connected if there is a path between any two vertices. $G$ is weakly connected if $\tilde{G}$ is connected. If $G$ is such that $E(G)$ is symmetric and $x$ is a vertex in $G$, then the subgraph $G_{x}$ consisting of all edges and vertices which are contained in some path beginning at $x$ is called the component of $G$ containing $x$. In this case $V\left(G_{x}\right)=[x]_{G}$, where $[x]_{G}$ is the equivalence class of the following relation $R$ defined on $V(G)$ by the rule:

$$
y R z \text { if there is a path in } G \text { from } y \text { to } z .
$$

Clearly, $G_{x}$ is connected.
Recently, J. Jakhymski [5] was the first author who gave sufficient conditions for an operator to be a PO if $(X, d)$ is endowed with a graph and defined the next concept:
Definition 1.1 ([5], Def. 2.1). We say that a mapping $f: X \rightarrow X$ is a Banach $G$-contraction or simply $G$-contraction if $f$ preserves edges of $G$, i.e.,

$$
\begin{equation*}
\forall x, y \in X((x, y) \in E(G) \Rightarrow(f(x), f(y)) \in E(G)) \tag{4}
\end{equation*}
$$

and $f$ decreases weights of edges of $G$ in the following way:

$$
\begin{equation*}
\exists \alpha \in(0,1), \forall x, y \in X((x, y) \in E(G) \Rightarrow d(f(x), f(y)) \leqslant \alpha d(x, y)) \tag{5}
\end{equation*}
$$

The main theorem is:
Theorem 1.2 ([5], Th 3.2). Let $(X, d)$ be complete, and let the triple $(X, d, G)$ have the following property:
$(P)$ for any $\left(x_{n}\right)_{n \in \mathbb{N}}$ in $X$, if $x_{n} \rightarrow x$ and $\left(x_{n}, x_{n+1}\right) \in E(G)$ for $n \in \mathbb{N}$ then there is a subsequence $\left(x_{k_{n}}\right)_{n \in \mathbb{N}}$ with $\left(x_{k_{n}}, x\right) \in E(G)$ for $n \in \mathbb{N}$.

Let $f: X \rightarrow X$ be a $G$-contraction, and $X_{f}=\{x \in X \mid(x, f x) \in E(G)\}$. Then the following statements hold.

1. cardFix $f=\operatorname{card}\left\{[x]_{\tilde{G}} \mid x \in X_{f}\right\}$.
2. Fix $f \neq \emptyset$ iff $X_{f} \neq \emptyset$.
3. $f$ has a unique fixed point iff there exists $x_{0} \in X_{f}$ such that $X_{f} \subseteq\left[x_{0}\right]_{\tilde{G}}$.
4. For any $x \in X_{f},\left.f\right|_{[x]_{\tilde{G}}}$ is a $P O$.
5. If $X_{f} \neq \emptyset$ and $G$ is weakly connected, then $f$ is a $P O$.
6. If $X^{\prime}:=\cup\left\{[x]_{\tilde{G}} \mid x \in G\right\}$ then $\left.f\right|_{X^{\prime}}$ is a WPO.
7. If $f \subseteq E(G)$, then $f$ is a WPO.

Here Fixf denotes the set of fixed points of operator $f$.
Since then several authors have considered the problem of existence and uniqueness of a fixed point for contraction type operators in metric spaces endowed with a graph (see [1], [2], [3], [9]).

## 2. Main results

Using Jachymski's Theorem [5] we can give alternate proofs to some known results by choosing the right form of graph.

Proposition 2.1. Banach's contraction principle is a consequence of Jakhymski's Theorem.

Proof. Let the graph $G_{0}$ defined by $V(G)=X$ and $E\left(G_{0}\right)=X \times X$, which is a connected graph and the contraction $T$ by Theorem 1.1 is a $G_{0}$-Banach contraction. The property ( P ) is fulfilled so from Theorem 1.1 the operator $T$ is PO.

In the following we prove that the fixed point theorems for contractions in partially ordered metric spaces are consequences of Jakhymski's Theorem.
Theorem 2.2 (Ran and Reurings [14], Th 2.1). Let (X,d) be a complete metric space endowed with a partial ordering " $\leq "$ such that

$$
\begin{equation*}
\text { every pair of, elements of } X \text { has an upper and a lower bound. } \tag{6}
\end{equation*}
$$

Let $T: X \rightarrow X$ be continuous and monotone, and such that

$$
\begin{equation*}
\exists \alpha \in(0,1) \forall x, y \in X(x \leqslant y \Rightarrow d(T x, T y) \leqslant \alpha d(x, y)) \tag{7}
\end{equation*}
$$

If there exists $x_{0} \in X$ with $x_{0} \leqslant T x_{0}$ or $T x_{0} \leqslant x_{0}$, then $T$ is a PO.
Proof. Let $G$ be the graph defined by $V(G)=X$ and

$$
E(G)=\{(x, y) \in X \times X \mid x \leq y\}
$$

Because every pair of elements of $X$ has an upper and a lower bound the graph $G$ is weakly connected. The mapping $T: X \rightarrow X$ which satisfies (7) and is monotone is a $G$-Banach contraction. From the continuity of mapping $T$ we get that the property $(\mathrm{P})$ is true so from Theorem 1.1 the operator $T$ is PO.

Further improvements of the above results were found independently by Petruşel and Rus [12], and Nieto and Rodríguez-López [11]. Here we give a slightly more general version of these extensions taken from the paper by Nieto, Pouso and RodríguezLópez [10]. Following [12] we denote:

$$
X_{\leq}:=\{(x, y) \in X \times X \mid x \leq y \text { or } y \leq x\}
$$

Theorem 2.3. Let $(X, d)$ be a complete metric space endowed with a partial ordering $" \leq "$ such that every pair of elements of $X$ has an upper or a lower bound. Let $T: X \rightarrow X$ be such that $T$ preserves comparable elements, i.e.

$$
\begin{equation*}
\text { for any } x, y \in X,(x, y) \in X_{\leq} \text {implies }(T x, T y) \in X_{\leq}, \tag{8}
\end{equation*}
$$

and (7) holds. Assume that either $T$ is orbitally continuous or $(X, d, \leq)$ is such that for any $\left(x_{n}\right)_{n \in \mathbb{N}}$, if $x_{n} \rightarrow x$ and $\left(x_{n}, x_{n+1}\right) \in X_{\leq}$, for $n \in \mathbb{N}$, then
there is a subsequence $\left(x_{k_{n}}\right)_{n \in \mathbb{N}}$ such $\left(x_{k_{n}}, x\right) \in X_{\leq} \forall n \in \mathbb{N}$.
If there exists $x_{0} \in X$ with $\left(x_{0}, T x_{0}\right) \in X_{\leq}$, then $T$ is a $P O$.
Proof. Let $G$ be the graph defined by $V(G)=X$ and

$$
E(G)=\{(x, y) \in X \times X \mid x \leq y \text { or } y \leq x\}
$$

Because every pair of elements of $X$ has an upper and a lower bound the graph $G$ is weakly connected. The mapping $T: X \rightarrow X$ which satisfies (7) and is monotone is a $G$-Banach contraction. From the orbitally continuity of mapping $T$ or by (9) we get the property $(\mathrm{P})$ is true so from Theorem 1.1 the operator $T$ is PO.

On the other hand, Theorem 1.1 yields directly the following well-known fixed point theorem which is quite different from the above results.

Theorem 2.4 (Edelstein, [7]). Let $(X, d)$ be complete and $\epsilon$-chainable for some $\epsilon>0$, i.e., given $x, y \in X$, there is $N \in \mathbb{N}$ and a sequence $\left(x_{i}\right)_{i=0}^{N}$ such that $x_{0}=x, x_{N}=y$ and $d\left(x_{i-1}, x_{i}\right)<\varepsilon$ for $i=1, \ldots, N$. Let $T: X \rightarrow X$ be such that

$$
\begin{equation*}
\exists \alpha \in(0,1), \forall x, y \in X(d(x, y)<\varepsilon \Rightarrow d(T x, T y) \leqslant \alpha d(x, y)) \tag{10}
\end{equation*}
$$

Then $T$ is a $P O$.
Proof. Clearly, (10) implies $T$ is continuous. Consider the graph $G$ with $V(G)=X$ and

$$
E(G)=\{(x, y) \in X \times X \mid d(x, y)<\varepsilon\}
$$

Then $\epsilon$-chainability of $(X, d)$ means $G$ is connected. If $(x, y) \in E(G)$, then

$$
d(T x, T y) \leqslant \alpha d(x, y) \leqslant \alpha \varepsilon \leqslant \varepsilon
$$

Hence (4) and (5) hold, so $T$ is a $G$-contraction. By Theorem 1.1, $T$ is a PO.
In the following we show the fixed point theorem for cyclic contractions proved in [8] by W.A. Kirk, P.S. Srinivasan and P. Veeramani is a consequence of Theorem 1.1.

Definition 2.1. Let $p \in \mathbb{N}, p \geq 2$ and $\left\{A_{i}\right\}_{i=1}^{p}$ be nonempty closed subsets of a complete metric space $(X, d)$. An operator $T:\left\{A_{i}\right\}_{i=1}^{p} \rightarrow\left\{A_{i}\right\}_{i=1}^{p}$ is called a cyclic operator if the following condition is satisfied:

$$
\begin{equation*}
T\left(A_{i}\right) \subseteq A_{i+1} \text { for all } i \in\{1,2, \ldots, p\} \tag{11}
\end{equation*}
$$

where $A_{p+1}=A_{1}$.
Theorem 2.5 ([8]). Let $p \in \mathbb{N}, p \geq 2$ and $\left\{A_{i}\right\}_{i=1}^{p}$ be nonempty closed subsets of $a$ complete metric space $(X, d)$, and suppose $T:\left\{A_{i}\right\}_{i=1}^{p} \rightarrow\left\{A_{i}\right\}_{i=1}^{p}$ satisfies (11) and the following one

$$
\begin{equation*}
d(T x, T y) \leqslant k d(x, y), \text { for all } x \in A_{i}, y \in A_{i+1}, 1 \leq i \leq p \tag{12}
\end{equation*}
$$

where $A_{p+1}=A_{1}$. If $k \in[0,1)$ then $T$ has an unique fixed point.
Proof. Consider the graph $G$ with $V(G)=X$ and

$$
E(G)=\left\{(x, y) \in X \times X \mid x \in A_{i} \text { si } y \in A_{i+1}, i=1, \ldots, p\right\}
$$

Because $T$ is a cyclic operator and $(x, y) \in E(G)$ then $x \in A_{i}$ and $y \in A_{i+1}$ so $T x \in A_{i+1}$ and $T y \in A_{i+2}$, which implies $(T x, T y) \in E(G)$. Using (12) we have $T$ is a $G$-contraction. From the definition of edges of $G$ we have that $G$ is weakly connected. Let $\left(x_{n}\right)_{n \in \mathbb{N}}$ in $X$, with $x_{n} \rightarrow x$ and $\left(x_{n}, x_{n+1}\right) \in E(G)$ for $n \in \mathbb{N}$. Then there is $j \in\{1,2, \ldots, n\}$ such that $x \in A_{j}$. However in view of (11) the sequence $\left\{x_{n}\right\}$ has an infinite number of terms in each $A_{i}$, for all $i \in\{1,2, \ldots, n\}$. The subsequence of the sequence $\left\{x_{n}\right\}$ formed by the terms which are in $A_{j-1}$ satisfies the condition (P) from Theorem 1.1. Obviously $X_{T} \neq \emptyset$ so $T$ is PO.

The last consequence of Jachymski's Theorem which we present is The Alternative of Fixed Point, due to Diaz and Margolis [4]. Here we will give a slightly more general version of these extensions taken from the paper by V. Radu [13].

Theorem 2.6 (The fixed point alternative). Suppose we are given a complete generalized metric space $(\Omega, d)$ and a strictly contractive mapping $T: \Omega \rightarrow \Omega$ with the Lipschitz constant $a$. Then, for each given element $x \in \Omega$, either

$$
d\left(T^{n} x, T^{n+1} x\right)=\infty, \forall n \geqslant 0
$$

or there exists a natural number $n_{0}$ such that
i. $d\left(T^{n} x, T^{n+1} x\right)<\infty$ for all $n \geqslant n_{0}$;
ii. The sequence $\left(T^{n} x\right)_{n \geqslant 0}$ is convergent to a fixed point $y *$ of $T$;
iii. $y *$ is the unique fixed point of $T$ in the set $\Delta=\left\{y \in \Omega \mid d\left(T^{n_{0}} x, y\right)<\infty\right\}$;
iv. $d(y, y *) \leqslant \frac{1}{1-a} d(y, T y)$ for all $y \in \Delta$.

Proof. Let the graph $G$ with $V(G)=X$ and

$$
E(G)=\{(x, y) \in X \times X \mid d(x, y)<\infty\}
$$

By the symmetry of distance we have $\tilde{G}=G$.
If $(x, y) \in E(G)$, so $d(x, y)<\infty$, then $d(T x, T y) \leqslant a d(x, y)<\infty$ in conclusion $(T x, T y) \in E(G)$, and $T$ being a strictly contractive mapping we have $T$ is a $G$ contraction.

Let $x \in X$ such that, there exists $n_{0} \in \mathbb{N}$ with property $d\left(T^{n_{0}} x, T^{n_{0}+1} x\right)<\infty$, then $\left(T^{n_{0}} x, T^{n_{0}+1} x\right) \in E(G)$, that is $T^{n_{0}} x \in X_{T}$ so

$$
X_{T} \neq \emptyset
$$

An easy induction shows

$$
d\left(T^{n} x, T^{n+1} x\right) \leqslant a^{n-n_{0}} d\left(T^{n_{0}} x, T^{n_{0}+1} x\right), \text { for all } n \geqslant n_{0}
$$

so $d\left(T^{n} x, T^{n+1} x\right)<\infty$ for all $n \geqslant n_{0}$, therefore the relation $i$. is true.
For the same $x$ like the one above, we have:

$$
\left[T^{n_{0}} x\right]_{G}=\{y \in X \mid \exists \text { a path in } G \text { from } x \text { to } y\}
$$

If $y \in\left[T^{n_{0}} x\right]_{G}$ then there is a path $\left(x_{i}\right)_{i=0}^{N}$ in $G$ from $T^{n_{0}} x$ to $y$, that is, $x_{0}=T^{n_{0}} x$, $x_{N}=y$ and $\left(x_{i-1}, x_{i}\right) \in E(G)$ for $i=1, \ldots, N$. Then

$$
d\left(T^{n_{0}} x, y\right) \leqslant \sum_{i=1}^{N} d\left(x_{i-1}, x_{i}\right)<\infty
$$

Consequently $\left[T^{n_{0}} x\right]_{G} \subseteq \Delta$ and the relation $\Delta \subseteq\left[T^{n_{0}} x\right]_{G}$ is obvious, so $\Delta=\left[T^{n_{0}} x\right]_{G}$.
If $\left(x_{n}\right)_{n \in \mathbb{N}}$ converges to $x^{*} \in X$ with property $\left(x_{n}, x_{n+1}\right) \in E(G)$ for all $n \in \mathbb{N}$ then for $\epsilon=1$ there exists $n_{\epsilon} \in \mathbb{N}$ such that $d\left(x_{n}, x^{*}\right)<1$ for all $n \geq n_{\epsilon}$, that is

$$
\left(x_{n}, x^{*}\right) \in E(G), \forall n \geqslant n_{\epsilon}
$$

The subsequence $\left(x_{n}\right)_{n \geqslant n_{0}}$ satisfies the condition (P) from Theorem 1.2. Then from Theorem 1.2, 4. we have $\left.T\right|_{\left[T^{n_{0}} x\right]_{G}}$ is PO which implies $i$ i. and $i i i$. from The Fixed Point Alternative.

For iv., let $y \in \Delta$ so $d\left(y, T^{n_{0}} x\right)<\infty$. Because $\left(T^{n} x\right)_{n \geqslant n_{0}}$ converges, then $d\left(T^{n_{0}} x, T^{n-1} x\right)<\infty$ for all $n>n_{0}$ and $d\left(y, T^{n-1} x\right)<\infty$, that is $\left(y, T^{n-1} x\right) \in$ $E(G)$. By the triangle inequality and because $T$ is a $G$-contraction, we get:

$$
\begin{equation*}
d\left(y, T^{n} x\right) \leqslant d(y, T y)+d\left(T y, T^{n} x\right) \leqslant d(y, T y)+a d\left(y, T^{n-1} x\right) \tag{13}
\end{equation*}
$$

for all $n \geq n_{0}$.
Hence, letting $n$ tend to $\infty$ in (13) we conclude

$$
d\left(y, y^{*}\right) \leqslant d(y, T y)+a d\left(y, y^{*}\right)
$$

that is $d\left(y, y^{*}\right) \leqslant \frac{1}{1-a} d(y, T y)$ for any $y \in \Delta$, which completes the proof.

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