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# On Jachymski's theorem

#### FLORIN BOJOR

ABSTRACT. In this note we prove that a fixed point theorem (due to Jachymski in [5]) extends and subsumes some results in the fixed point theory.

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### 1. Introduction

The classical Banachs contraction principle is one of the most useful results in fixed point theory. In a metric space setting it can be briefly stated as follows.

**Theorem 1.1.** Let (X,d) be a complete metric space and  $T : X \to X$  a strict contraction, *i.e.* a map satisfying

$$d(Tx, Ty) \leq ad(x, y), for all x, y \in X,$$
(1)

where 0 < a < 1 is constant. Then:

(1) T has a unique fixed point  $x^*$  in X;

(2) The Picard iteration  $(x_n)_{n\geq 0}$  defined by

$$x_{n+1} = Tx_n, n = 0, 1, 2, \dots$$
<sup>(2)</sup>

converges to  $x^*$ , for any  $x_0 \in X$ .

There is more than one way to generalize the Banach's contraction mapping principle. One of them is to get the subset M of  $X \times X$ , the contraction condition to be satisfied only for  $(x, y) \in M$  and still the operator is the operator is a Picard operator (abbr. PO). This article will prove that the Jachymski's theorem is one of the most general theorems of its kind.

Let T be a selfmap of a metric space (X, d). Following Petruşel and Rus [12], we say that T is a *Picard operator* if T has a unique fixed point  $x^*$  and  $\lim_{n\to\infty} T^n x = x^*$  for all  $x \in X$  and T is a *weakly Picard operator* (abbr. WPO) if the sequence  $(T^n x)_{n\in\mathbb{N}}$  converges, for all  $x \in X$  and the limit (which may depend on x) is a fixed point of T. Thus any contraction on complete metric space is PO.

Let (X, d) be a metric space. Let  $\Delta$  denote the diagonal of the Cartesian product  $X \times X$ . Consider a directed graph G such that the set V(G) of its vertices coincides with X, and the set E(G) of its edges contains all loops, i.e.,  $E(G) \supseteq \Delta$ . We assume G has no parallel edges, so we can identify G with the pair (V(G), E(G)). Moreover, we may treat G as a weighted graph (see [[6], p. 309]) by assigning to each edge the

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distance between its vertices. By  $G^{-1}$  we denote the conversion of graph G, i.e. the graph obtained from G by reversing the direction of edges. Thus we have

$$E(G^{-1}) = \{(x, y) | (y, x) \in G\}.$$

The letter  $\tilde{G}$  denotes the undirected graph obtained from G by ignoring the direction of edges. Actually, it will be more convenient for us to treat  $\tilde{G}$  as a directed graph for which the set of its edges is symmetric. Under this convention,

$$E\left(\tilde{G}\right) = E\left(G\right) \cup E\left(G^{-1}\right) \tag{3}$$

We call (V', E') a subgraph of G if  $V' \subseteq V(G)$ ,  $E' \subseteq E(G)$  and for any edge  $(x, y) \in E'$ ,  $x, y \in V'$ .

Now we recall a few basic notions concerning the connectivity of graphs. All of them can be found, e.g., in [6]. If x and y are vertices in a graph G, then a path in G from x to y of length N ( $N \in \mathbb{N}$ ) is a sequence  $(x_i)_{i=0}^N$  of N + 1 vertices such that  $x_0 = x, x_N = y$  and  $(x_{i-1}, x_i) \in E(G)$  for i = 1, ..., N. A graph G is connected if there is a path between any two vertices. G is weakly connected if  $\tilde{G}$  is connected. If G is such that E(G) is symmetric and x is a vertex in G, then the subgraph  $G_x$ consisting of all edges and vertices which are contained in some path beginning at x is called the component of G containing x. In this case  $V(G_x) = [x]_G$ , where  $[x]_G$  is the equivalence class of the following relation R defined on V(G) by the rule:

yRz if there is a path in G from y to z.

Clearly,  $G_x$  is connected.

Recently, J. Jakhymski [5] was the first author who gave sufficient conditions for an operator to be a PO if (X, d) is endowed with a graph and defined the next concept: **Definition 1.1** ([5], Def. 2.1). We say that a mapping  $f : X \to X$  is a *Banach G-contraction* or simply *G-contraction* if f preserves edges of G, i.e.,

$$\forall x, y \in X ((x, y) \in E(G) \Rightarrow (f(x), f(y)) \in E(G))$$

$$\tag{4}$$

and f decreases weights of edges of G in the following way:

$$\exists \alpha \in (0,1), \forall x, y \in X ((x,y) \in E(G) \Rightarrow d(f(x), f(y)) \leq \alpha d(x,y)).$$
(5)

The main theorem is:

**Theorem 1.2** ([5], Th 3.2). Let (X, d) be complete, and let the triple (X, d, G) have the following property:

(P) for any  $(x_n)_{n\in\mathbb{N}}$  in X, if  $x_n \to x$  and  $(x_n, x_{n+1}) \in E(G)$  for  $n \in \mathbb{N}$  then there is a subsequence  $(x_{k_n})_{n\in\mathbb{N}}$  with  $(x_{k_n}, x) \in E(G)$  for  $n \in \mathbb{N}$ .

Let  $f: X \to X$  be a G-contraction, and  $X_f = \{x \in X | (x, fx) \in E(G)\}$ . Then the following statements hold.

- 1. card  $Fix f = \text{card} \{ [x]_{\tilde{G}} | x \in X_f \}.$
- 2. Fix  $f \neq \emptyset$  iff  $X_f \neq \overline{\emptyset}$ .
- 3. *f* has a unique fixed point iff there exists  $x_0 \in X_f$  such that  $X_f \subseteq [x_0]_{\tilde{G}}$ .
- 4. For any  $x \in X_f$ ,  $f|_{[x]_{\tilde{G}}}$  is a PO.
- 5. If  $X_f \neq \emptyset$  and G is weakly connected, then f is a PO.
- 6. If  $X' := \bigcup \{ [x]_{\tilde{G}} | x \in G \}$  then  $f |_{X'}$  is a WPO.
- 7. If  $f \subseteq E(G)$ , then f is a WPO.

Here Fixf denotes the set of fixed points of operator f.

Since then several authors have considered the problem of existence and uniqueness of a fixed point for contraction type operators in metric spaces endowed with a graph (see [1], [2], [3], [9]).

### 2. Main results

Using Jachymski's Theorem [5] we can give alternate proofs to some known results by choosing the right form of graph.

**Proposition 2.1.** Banach's contraction principle is a consequence of Jakhymski's Theorem.

*Proof.* Let the graph  $G_0$  defined by V(G) = X and  $E(G_0) = X \times X$ , which is a connected graph and the contraction T by Theorem 1.1 is a  $G_0$ -Banach contraction. The property (P) is fulfilled so from Theorem 1.1 the operator T is PO.

In the following we prove that the fixed point theorems for contractions in partially ordered metric spaces are consequences of Jakhymski's Theorem.

**Theorem 2.2** (Ran and Reurings [14], Th 2.1). Let (X, d) be a complete metric space endowed with a partial ordering "  $\leq$  " such that

every pair of, elements of X has an upper and a lower bound. (6)

Let  $T: X \to X$  be continuous and monotone, and such that

$$\exists \alpha \in (0,1) \ \forall x, y \in X \ (x \leqslant y \Rightarrow d \ (Tx, Ty) \leqslant \alpha d \ (x, y)) \ . \tag{7}$$

If there exists  $x_0 \in X$  with  $x_0 \leq Tx_0$  or  $Tx_0 \leq x_0$ , then T is a PO.

*Proof.* Let G be the graph defined by V(G) = X and

$$E(G) = \{(x, y) \in X \times X \mid x \le y\}$$

Because every pair of elements of X has an upper and a lower bound the graph G is weakly connected. The mapping  $T: X \to X$  which satisfies (7) and is monotone is a G-Banach contraction. From the continuity of mapping T we get that the property (P) is true so from Theorem 1.1 the operator T is PO.

Further improvements of the above results were found independently by Petruşel and Rus [12], and Nieto and Rodríguez-López [11]. Here we give a slightly more general version of these extensions taken from the paper by Nieto, Pouso and Rodríguez-López [10]. Following [12] we denote:

$$X_{\leq} := \{ (x, y) \in X \times X \, | \, x \leq y \text{ or } y \leq x \, \} \, .$$

**Theorem 2.3.** Let (X, d) be a complete metric space endowed with a partial ordering "  $\leq$  " such that every pair of elements of X has an upper or a lower bound. Let  $T: X \to X$  be such that T preserves comparable elements, i.e.

for any 
$$x, y \in X, (x, y) \in X_{\leq}$$
 implies  $(Tx, Ty) \in X_{\leq}$ , (8)

and (7) holds. Assume that either T is orbitally continuous or  $(X, d, \leq)$  is such that

for any 
$$(x_n)_{n \in \mathbb{N}}$$
, if  $x_n \to x$  and  $(x_n, x_{n+1}) \in X_{\leq}$ , for  $n \in \mathbb{N}$ , then  
there is a subsequence  $(x_{k_n})_{n \in \mathbb{N}}$  such  $(x_{k_n}, x) \in X_{\leq} \forall n \in \mathbb{N}$ . (9)

If there exists  $x_0 \in X$  with  $(x_0, Tx_0) \in X_{\leq}$ , then T is a PO.

*Proof.* Let G be the graph defined by V(G) = X and

$$E(G) = \{(x, y) \in X \times X \mid x \le y \text{ or } y \le x\}.$$

Because every pair of elements of X has an upper and a lower bound the graph G is weakly connected. The mapping  $T: X \to X$  which satisfies (7) and is monotone is a G-Banach contraction. From the orbitally continuity of mapping T or by (9) we get the property (P) is true so from Theorem 1.1 the operator T is PO.

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On the other hand, Theorem 1.1 yields directly the following well-known fixed point theorem which is quite different from the above results.

**Theorem 2.4** (Edelstein, [7]). Let (X, d) be complete and  $\epsilon$ -chainable for some  $\epsilon > 0$ , i.e., given  $x, y \in X$ , there is  $N \in \mathbb{N}$  and a sequence  $(x_i)_{i=0}^N$  such that  $x_0 = x, x_N = y$  and  $d(x_{i-1}, x_i) < \epsilon$  for i = 1, ..., N. Let  $T : X \to X$  be such that

$$\exists \alpha \in (0,1), \, \forall x, y \in X \, (d \, (x,y) < \varepsilon \Rightarrow d \, (Tx,Ty) \leqslant \alpha d \, (x,y)) \,. \tag{10}$$

Then T is a PO.

*Proof.* Clearly, (10) implies T is continuous. Consider the graph G with V(G) = X and

$$E(G) = \{(x, y) \in X \times X | d(x, y) < \varepsilon\}$$

Then  $\epsilon$ -chainability of (X, d) means G is connected. If  $(x, y) \in E(G)$ , then

$$d\left(Tx,Ty\right) \leqslant \alpha d\left(x,y\right) \leqslant \alpha \varepsilon \leqslant \varepsilon.$$

Hence (4) and (5) hold, so T is a G-contraction. By Theorem 1.1, T is a PO.  $\Box$ 

In the following we show the fixed point theorem for cyclic contractions proved in [8] by W.A. Kirk, P.S. Srinivasan and P. Veeramani is a consequence of Theorem 1.1.

**Definition 2.1.** Let  $p \in \mathbb{N}$ ,  $p \geq 2$  and  $\{A_i\}_{i=1}^p$  be nonempty closed subsets of a complete metric space (X, d). An operator  $T : \{A_i\}_{i=1}^p \to \{A_i\}_{i=1}^p$  is called a *cyclic operator* if the following condition is satisfied:

$$\Gamma(A_i) \subseteq A_{i+1} \text{ for all } i \in \{1, 2, ..., p\},$$
(11)

where  $A_{p+1} = A_1$ .

**Theorem 2.5** ([8]). Let  $p \in \mathbb{N}$ ,  $p \geq 2$  and  $\{A_i\}_{i=1}^p$  be nonempty closed subsets of a complete metric space (X, d), and suppose  $T : \{A_i\}_{i=1}^p \to \{A_i\}_{i=1}^p$  satisfies (11) and the following one

$$d(Tx, Ty) \leq kd(x, y), \text{ for } all x \in A_i, y \in A_{i+1}, 1 \leq i \leq p,$$

$$(12)$$

where  $A_{p+1} = A_1$ . If  $k \in [0, 1)$  then T has an unique fixed point.

*Proof.* Consider the graph G with V(G) = X and

$$E(G) = \{(x, y) \in X \times X | x \in A_i \text{ si } y \in A_{i+1}, i = 1, ..., p\}$$

Because T is a cyclic operator and  $(x, y) \in E(G)$  then  $x \in A_i$  and  $y \in A_{i+1}$  so  $Tx \in A_{i+1}$  and  $Ty \in A_{i+2}$ , which implies  $(Tx, Ty) \in E(G)$ . Using (12) we have T is a G-contraction. From the definition of edges of G we have that G is weakly connected. Let  $(x_n)_{n\in\mathbb{N}}$  in X, with  $x_n \to x$  and  $(x_n, x_{n+1}) \in E(G)$  for  $n \in \mathbb{N}$ . Then there is  $j \in \{1, 2, ..., n\}$  such that  $x \in A_j$ . However in view of (11) the sequence  $\{x_n\}$  has an infinite number of terms in each  $A_i$ , for all  $i \in \{1, 2, ..., n\}$ . The subsequence of the sequence  $\{x_n\}$  formed by the terms which are in  $A_{j-1}$  satisfies the condition (P) from Theorem 1.1. Obviously  $X_T \neq \emptyset$  so T is PO.

The last consequence of Jachymski's Theorem which we present is The Alternative of Fixed Point, due to Diaz and Margolis [4]. Here we will give a slightly more general version of these extensions taken from the paper by V. Radu [13].

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**Theorem 2.6** (The fixed point alternative). Suppose we are given a complete generalized metric space  $(\Omega, d)$  and a strictly contractive mapping  $T : \Omega \to \Omega$  with the Lipschitz constant a. Then, for each given element  $x \in \Omega$ , either

$$d\left(T^{n}x, T^{n+1}x\right) = \infty, \ \forall n \ge 0,$$

or there exists a natural number  $n_0$  such that

i.  $d(T^n x, T^{n+1} x) < \infty$  for all  $n \ge n_0$ ;

ii. The sequence  $(T^n x)_{n \ge 0}$  is convergent to a fixed point y \* of T;

iii.  $y^*$  is the unique fixed point of T in the set  $\Delta = \{y \in \Omega | d(T^{n_0}x, y) < \infty\};$ 

iv.  $d(y, y^*) \leq \frac{1}{1-a}d(y, Ty)$  for all  $y \in \Delta$ .

*Proof.* Let the graph G with V(G) = X and

$$E(G) = \{(x, y) \in X \times X | d(x, y) < \infty\}.$$

By the symmetry of distance we have  $\tilde{G} = G$ .

If  $(x, y) \in E(G)$ , so  $d(x, y) < \infty$ , then  $d(Tx, Ty) \leq ad(x, y) < \infty$  in conclusion  $(Tx, Ty) \in E(G)$ , and T being a strictly contractive mapping we have T is a G-contraction.

Let  $x \in X$  such that, there exists  $n_0 \in \mathbb{N}$  with property  $d(T^{n_0}x, T^{n_0+1}x) < \infty$ , then  $(T^{n_0}x, T^{n_0+1}x) \in E(G)$ , that is  $T^{n_0}x \in X_T$  so

$$X_T \neq \emptyset.$$

An easy induction shows

$$d(T^n x, T^{n+1} x) \leq a^{n-n_0} d(T^{n_0} x, T^{n_0+1} x)$$
, for all  $n \geq n_0$ 

so  $d(T^n x, T^{n+1} x) < \infty$  for all  $n \ge n_0$ , therefore the relation *i*. is true.

For the same x like the one above, we have:

$$[T^{n_0}x]_G = \{y \in X \mid \exists a \text{ path in } G \text{ from } x \text{ to } y\}.$$

If  $y \in [T^{n_0}x]_G$  then there is a path  $(x_i)_{i=0}^N$  in G from  $T^{n_0}x$  to y, that is,  $x_0 = T^{n_0}x$ ,  $x_N = y$  and  $(x_{i-1}, x_i) \in E(G)$  for i = 1, ..., N. Then

$$d\left(T^{n_0}x,y\right) \leqslant \sum_{i=1}^{N} d\left(x_{i-1},x_i\right) < \infty.$$

Consequently  $[T^{n_0}x]_G \subseteq \Delta$  and the relation  $\Delta \subseteq [T^{n_0}x]_G$  is obvious, so  $\Delta = [T^{n_0}x]_G$ .

If  $(x_n)_{n \in \mathbb{N}}$  converges to  $x^* \in X$  with property  $(x_n, x_{n+1}) \in E(G)$  for all  $n \in \mathbb{N}$ then for  $\epsilon = 1$  there exists  $n_{\epsilon} \in \mathbb{N}$  such that  $d(x_n, x^*) < 1$  for all  $n \ge n_{\epsilon}$ , that is

 $(x_n, x^*) \in E(G), \forall n \ge n_{\epsilon}.$ 

The subsequence  $(x_n)_{n \ge n_0}$  satisfies the condition (P) from Theorem 1.2. Then from Theorem 1.2, 4. we have  $T|_{[T^{n_0}x]_G}$  is PO which implies *ii*. and *iii*. from The Fixed Point Alternative.

For *iv.*, let  $y \in \Delta$  so  $d(y, T^{n_0}x) < \infty$ . Because  $(T^n x)_{n \ge n_0}$  converges, then  $d(T^{n_0}x, T^{n-1}x) < \infty$  for all  $n > n_0$  and  $d(y, T^{n-1}x) < \infty$ , that is  $(y, T^{n-1}x) \in E(G)$ . By the triangle inequality and because T is a G-contraction, we get:

$$d(y,T^{n}x) \leq d(y,Ty) + d(Ty,T^{n}x) \leq d(y,Ty) + ad(y,T^{n-1}x), \qquad (13)$$

for all  $n \ge n_0$ .

Hence, letting n tend to  $\infty$  in (13) we conclude

$$d(y, y^*) \leqslant d(y, Ty) + ad(y, y^*)$$

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that is  $d(y, y^*) \leq \frac{1}{1-a}d(y, Ty)$  for any  $y \in \Delta$ , which completes the proof.

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(Florin Bojor) DEPARTMENT OF MATHEMATICS AND COMPUTER SCIENCE, FACULTY OF SCIENCES NORTH UNIVERSITY CENTER AT BAIA MARE, TECHNICAL UNIVERSITY OF CLUJ-NAPOCA, VICTORIEI Nr. 76, 430122 Baia Mare ROMANIA E-mail address: florin.bojor@yahoo.com

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