# Iterative method for computing a Schur form of symplectic matrix 

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#### Abstract

We present in this paper a constructive iterative method to compute an orthogonal and symplectic Schur form. This structured Schur form reduction is used to compute eigenvalues and invariant subspaces of symplectic matrices.

Key words and phrases. Symplectic matrix, Symplectic reflector, ortho- $S R$ decomposition, Schur decomposition.


## 1. Introduction

The computation of the eigenvalues and eigenvectors of matrices play important roles in many applications in the physical sciences. For example, they play a prominent role in image processing applications. Measurement of image sharpness can be done using the concept of eigenvalues [6]. In this paper we are interesting in a structured eigenvalue problem. We propose a practical method to compute eigenvalues and invariant subspaces for symplectic matrices witch are of particular importance in applications such as optimal control [7, 8]. Symplectic matrices are widely used in SR factorization witch is a principal step in structure-preserving methods. It is a longstanding open problem to compute the eigenvalues and the Schur form in particular the one how preserved the structure [3, 4]. In the case of an eigenvalue problem of structured matrices, the preservation of this structure may help exploit the symmetry of the problem and to improve the accuracy and efficiency calculations of invariant subspaces and eigenvalues [5]. Our proposed method here is based on an orthogonal and symplectic SR factorization based on orthogonal and symplectic reflectors. Orthogonality is used to preserve the stability and Symplecticity is used to preserve the structure. In paragraph 3, we give and prove an orthogonal and symplectic Schur form theorem for real symplectic matrix. An algorithm that compute this structured Schur form reduction is given and numerical experimental results are presented to illustrate the effectiveness of our approach.

## 2. Terminology, notation and some basic facts

In this section we collect several well-known properties of structured matrices, for future reference.

An ubiquitous matrix in this work is the skew-symmetric matrix $J_{2 n}=\left(\begin{array}{cc}O_{n} & I_{n} \\ -I_{n} & O_{n}\end{array}\right)$, where $I_{n}$ and $O_{n}$ are the $n \times n$ identity and zero matrix, respectively. Note that $J_{2 n}^{-1}=J_{2 n}^{T}=-J_{2 n}$. In the following, we will drop the

[^0]subscript $n$ and $2 n$ whenever the dimension of corresponding matrix is clear from its context. The $J$-transpose of any $2 n$-by- $2 p$ matrix $M$ is defined by $M^{J}=J_{2 p}^{T} M^{T} J_{2 n} \in$ $\mathbb{R}^{2 p \times 2 n}$. Any matrix $S \in \mathbb{R}^{2 n \times 2 p}$ satisfying the property $S^{T} J_{2 n} S=J_{2 p}\left(S^{J} S=I_{2 p}\right)$ is called symplectic matrix. This property is also called $J$-orthogonality. The symplectic similarity transformations preserve structured matrix.

Remark 2.1. An augmented matrix

$$
S=\left(\begin{array}{cccc}
I & 0 & 0 & 0 \\
0 & P_{11} & 0 & P_{12} \\
0 & 0 & I & 0 \\
0 & P_{21} & 0 & P_{22}
\end{array}\right)
$$

is symplectic if and only if the matrix $P=\left(\begin{array}{ll}P_{11} & P_{12} \\ P_{21} & P_{22}\end{array}\right)$ is symplectic.
2.1. Symplectic reflectors. Setting $E_{i}=\left[\begin{array}{ll}e_{i} & e_{n+i}\end{array}\right] \in \mathbb{R}^{2 n \times 2}$ for $i=1, \cdots, n$ where $e_{i}$ is the $i$-th element of the canonical basis of $\mathbb{R}^{2 n}$. We then obtain

$$
E_{i}^{J}=E_{i}^{T} \text { and } E_{i}^{J} E_{j}=\delta_{i j} I_{2}
$$

where $\delta_{i j}= \begin{cases}1 & \text { if } i=j, \\ 0 & \text { if } i \neq j .\end{cases}$
We recall the symplectic reflector on $\mathbb{R}^{2 n \times 2}$ (see $[1,2]$ ), which is defined in parallel with elementary reflectors.
Proposition 2.1. Let $U, V$ be two $2 n$-by-2 real matrices satisfying $U^{J} U=V^{J} V=I_{2}$. If the 2-by-2 matrix $C=I_{2}+V^{J} U$ is nonsingular, then, the transformation $S=(U+$ $V) C^{-1}(U+V)^{J}-I_{2 n}$ is symplectic and takes $U$ to $V$. It's called a symplectic reflector. Additionally, if $U^{J}=U^{T}$ and $V^{J}=V^{T}$, then $S$ is orthogonal and symplectic.
Proposition 2.2. Let $u \in \mathbb{R}^{2 n}$ be a nonzero $2 n$-component real vector. The reflector

$$
S=\left(U+\sqrt{\alpha} E_{1}\right)\left(\alpha I_{2}+\sqrt{\alpha} E_{1}^{J} U\right)^{-1}\left(U+\sqrt{\alpha} E_{1}\right)^{J}-I_{2 n}
$$

where $U=[u-J u]$, is orthogonal and symplectic and verify $S u=\sqrt{\alpha} e_{1}$ where $\alpha=u^{T} u=\|u\|_{2}^{2}$.

Proof. Since $U^{J} U=\alpha I_{2}$ with $\alpha=u^{T} u=\|u\|_{2}^{2}>0$, then a simple calculation gives the result.

### 2.2. Symplectic matrices.

Proposition 2.3. If $M \in \mathbb{R}^{2 n \times 2 n}$ is symplectic then $M^{T}$ is symplectic.
Proof. Since

$$
\begin{aligned}
M J M^{T} & =M J\left(M^{T} J M\right) M^{-1} J^{-1} \\
& =M J J M^{-1} J^{-1} \\
& =-I_{n} J^{-1} \\
& =J \\
M^{T} J M=J \Rightarrow M J M^{T} & =M J\left(M^{T} J M\right) M^{-1} J^{-1}= \\
& =M J J M^{-1} J^{-1}=-I_{n} J^{-1}=J
\end{aligned}
$$

This proves that $M^{T}$ is symplectic.

Proposition 2.4. If $M=\left(\begin{array}{cc}A & C \\ B & D\end{array}\right) \in \mathbb{R}^{2 n \times 2 n}$ where $A, B, C, D \in \mathbb{R}^{n \times n}$, then $M$ is symplectic if and only if the matrices $A, B, C, D$ verify :

$$
\left\{\begin{array}{c}
A^{T} B \text { and } C^{T} D \text { are symmetric, } \\
A^{T} D-B^{T} C=I_{n}
\end{array}\right.
$$

Proof. We have

$$
M^{T} J M=\left(\begin{array}{cc}
B^{T} A-A^{T} B & B^{T} C-A^{T} D \\
D^{T} A-C^{T} B & D^{T} C-C^{T} D
\end{array}\right)
$$

Then

$$
\begin{aligned}
M \text { is symplectic } & \Leftrightarrow\left\{\begin{array}{c}
B^{T} A=A^{T} B \text { and } D^{T} C=C^{T} D \\
A^{T} D-B^{T} C=D^{T} A-C^{T} B=I_{n}
\end{array}\right. \\
& \Leftrightarrow\left\{\begin{array}{c}
A^{T} B \text { and } C^{T} D \text { are symmetric } \\
A^{T} D-B^{T} C=I_{n} .
\end{array}\right.
\end{aligned}
$$

Theorem 2.5. A matrix $M \in \mathbb{R}^{2 n \times 2 n}$ is orthogonal and symplectic if and only if $M$ is in the following form

$$
M=\left(\begin{array}{cc}
A & -B \\
B & A
\end{array}\right)
$$

where $A, B \in \mathbb{R}^{n \times n}$ verify

$$
\left\{\begin{array}{c}
A^{T} B \text { is symmetric } \\
A^{T} A+B^{T} B=I_{n}
\end{array}\right.
$$

Proof. If $M=\left(\begin{array}{cc}A & C \\ B & D\end{array}\right)$ is orthogonal and symplectic, where $A, B, C, D \in \mathbb{R}^{n \times n}$, then

$$
J=M J M^{T}=M J M^{-1}
$$

That proves $J M=M J$. Then $C=-B$ and $D=A$. By the result of Proposition $2.4, A, B \in \mathbb{R}^{n \times n}$ verify

$$
\left\{\begin{array}{c}
A^{T} B \text { is symmetric } \\
A^{T} A+B^{T} B=I_{n}
\end{array}\right.
$$

2.3. Ortho-SR decomposition. By using ortho-symplectic reflectors defined above, we decompose a symplectic real $2 n$-by- $2 n$ matrix $A$ on the form $A=S R$ where $S \in \mathbb{R}^{2 n \times 2 n}$ is orthogonal and symplectic and $R$ is symplectic and is in the following form

$$
R=\left(\begin{array}{cccc}
\stackrel{\mid c c c c}{\star} n & \star & \cdots & \star  \tag{1}\\
0 & * & \ddots & \vdots \\
\vdots & \ddots & \ddots & * \\
0 & \cdots & 0 & *
\end{array} \left\lvert\, \begin{array}{|ccccc}
* & * & \cdots & * \\
* & * & \ddots & \vdots \\
\vdots & \ddots & \ddots & * \\
* & \cdots & * & * \\
\hline \left.\begin{array}{ccccc}
* & 0 & \cdots & 0 \\
0 & \ddots & \ddots & \vdots \\
\vdots & \ddots & \ddots & 0 \\
0 & \cdots & 0 & 0
\end{array} \right\rvert\, & \cdots & 0 \\
* & * & \ddots & \vdots \\
\vdots & \ddots & \ddots & 0 \\
* & \cdots & * & *
\end{array}\right.\right) .
$$

## Algorithm : Ortho-symplectic $S R$-decomposition

## Hereafter, Matlab notations are used

Input : $A \in \mathbb{R}^{2 n \times 2 n}$ a symplectic matrix
Output: A $2 n \times 2 n$ orthogonal and symplectic matrix $S$ and a symplectic matrix $R$ in the form (1) such that $A=S R$ For $\mathrm{k}=1$ to n do
$u:=A(:, k) ; E_{k}=\left[e_{k},-J e_{k}\right] ; I=\operatorname{eye}(2 n) ;$
$I_{k}=\operatorname{blkdiag}(-\operatorname{eye}(k)$, eye $(n-k),-\operatorname{eye}(k)$, eye $(n-k))$
For $\mathrm{j}=1$ to $\mathrm{k}-1$ do

$$
u(j)=0 ; u(n+j)=0
$$

end For
If $(\|u\| \neq 0)$ then

$$
u=\frac{u}{\|u\|}
$$

$$
U=(u,-J u)
$$

$$
C=I-2 E_{k}^{J} U
$$

$$
\text { If }(\operatorname{det} C \neq 0) \text { then }
$$

$$
T=(U+E) C^{-1}\left(U+E_{k}\right)^{J}-I_{k}
$$

else

$$
C=I+2 E^{J} U
$$

$$
T=(U+E) C^{-1}\left(U+E_{k}\right)^{J}+I
$$

end If $S:=S T ; A:=T A$
end If
end For

## 3. Ortho-symplectic Schur form

Lemma 3.1. If $A$ is a symplectic matrix and $u \in \mathbb{C}^{2 n}$ an eigenvector corresponding to an eigenvalue $\lambda$ of $A$. Suppose that $\lambda$ is outside the unit circle, then there exists an unitary and symplectic reflector $S$ such that $S u=\alpha e_{1}$.
Proof. Let $u$ be an eigenvector corresponding to an eigenvalue $\lambda$ of $A$ such that $|\lambda| \neq 1$ and $\|u\|=1$.
$U=[u,-J \bar{u}] \in \mathbb{C}^{2 n \times 2}$ is unitary and symplectic $\left(U^{H} U=U^{J} U=I_{2}\right)$. Indeed,

$$
U^{J} U=J^{T} U^{H} J U=\left(\begin{array}{cc}
0 & -1 \\
1 & 0
\end{array}\right)\left(\begin{array}{cc}
u^{H} J u & u^{H} u \\
-u^{H} u & u^{H} J u
\end{array}\right)=\left(\begin{array}{cc}
\|u\|^{2} & u^{H} J u \\
-u^{H} J u & \|u\|^{2}
\end{array}\right) .
$$

The matrix $A$ is symplectic, then $A^{H} J A=J$ and,

$$
u^{H} J u=\frac{1}{|\lambda|^{2}}(A u)^{H} J A u=\frac{1}{|\lambda|^{2}} u^{H} J u
$$

Since $|\lambda| \neq 1$, then $u^{H} J u=0$. Let set $N=E_{1}^{J} U$. If -1 is not eigenvalue of the 2-by-2 matrix $N$, then the reflector $S=\left(U+E_{1}\right)\left(I_{2}+E_{1}^{J} U\right)^{-1}\left(U+E_{1}\right)^{J}-I_{2 n}$ is
unitary and symplectic and verify $S U=\alpha E_{1}$. Then $S u=\alpha e_{1}$ ( here $\alpha=1$ ). If -1 is eigenvalue of $N$, then 1 is not eigenvalue of $E_{1}^{J} U$. Indeed, we have $E_{1}^{J} U=$ $\left(\begin{array}{cc}e_{1}^{T} u & -e_{1}^{T} J \bar{u} \\ e_{n+1}^{T} u & -e_{n+1}^{T} J \bar{u}\end{array}\right)=\left(\begin{array}{cc}u_{1} & -\overline{u_{n+1}} \\ u_{n+1} & \overline{u_{1}}\end{array}\right)$ then $\operatorname{det}\left(E_{1}^{J} U\right)=\left|u_{1}\right|^{2}+\left|u_{n+1}\right|^{2} \geq 0$. The reflector $S=\left(U-E_{1}\right)\left(I_{2}-E_{1}^{J} U\right)^{-1}\left(U-E_{1}\right)^{J}-I_{2 n}$ is unitary and symplectic and verify $S U=\alpha E_{1}$ and then $S u=\alpha e_{1}$ ( here $\alpha=-1$ ).

Theorem 3.2. Let $A$ be a $2 n-b y-2 n$ real symplectic matrix such that all eigenvalues of $A$ are outside the unit circle. Then there exists an unitary and symplectic matrix $Q$ such that $A=Q R Q^{T}$ where $R$ is symplectic and is in the following form

Proof. The proof can be seen by using the principe of induction on $n$.
Let $\lambda$ be an eigenvalue of $A$ and $u$ a normalized corresponding eigenvector. $U=$ $[u,-J u] \in \mathbb{R}^{2 n \times 2}$ is unitary and symplectic $\left(U^{H} U=U^{J} U=I\right)$. From Lemma 3.1 there exists an unitary and symplectic reflector $S_{1}$ such that $S_{1} u=\alpha e_{1}$ and then

$$
S_{1} A S_{1}^{T} e_{1}=\lambda e_{1}
$$

The matrix $R_{1}=S_{1} A S_{1}^{H}$ is symplectic and it is in the following form

The matrix $R_{2}=\left(\begin{array}{cc}A & B \\ C & D\end{array}\right)$ is also symplectic. Indeed,

$$
R_{1}=\left(\begin{array}{ll}
A^{\prime} & B^{\prime} \\
C^{\prime} & D^{\prime}
\end{array}\right), A^{\prime}, B^{\prime}, C^{\prime}, D^{\prime} \in \mathbb{R}^{n \times n}
$$

We have

$$
R_{1}^{T} J R_{1}=\left(\begin{array}{cc}
C^{\prime T} A^{\prime}-A^{\prime T} C^{\prime} & C^{\prime T} B^{\prime}-A^{\prime T} D^{\prime} \\
D^{\prime T} A^{\prime}-B^{\prime T} C^{\prime} & D^{\prime T} B^{\prime}-B^{\prime T} D^{\prime}
\end{array}\right)
$$

And

$$
R_{2}^{T} J R_{2}=\left(\begin{array}{cc}
C^{T} A-A^{T} C & C^{T} B-A^{T} D \\
D^{T} A-B^{T} C & D^{T} B-B^{T} D
\end{array}\right)
$$

By block multiplication, we have

$$
\begin{aligned}
C^{\prime T} A^{\prime}-A^{\prime T} C^{\prime} & =\left(\begin{array}{rr}
0 & O \\
0 & C^{T} A-A^{T} C
\end{array}\right), C^{\prime T} B^{\prime}-A^{\prime T} D^{\prime}=\left(\begin{array}{rr}
-1 & 0 \\
X & C^{T} B-A^{T} D
\end{array}\right) \\
D^{\prime T} B^{\prime}-B^{\prime T} D^{\prime} & =\left(\begin{array}{rr}
x & X \\
X & D^{T} B-A^{T} D
\end{array}\right), D^{\prime T} A^{\prime}-B^{\prime T} C^{\prime}=\left(\begin{array}{rr}
1 & X \\
X & D^{T} A-B^{T} C
\end{array}\right) .
\end{aligned}
$$

$R_{1}$ is symplectic then $R_{1}^{T} J R_{1}=J$ and

$$
\begin{aligned}
C^{T} A^{\prime}-A^{\prime T} C^{\prime}=0, & C^{\prime T} B^{\prime}-A^{\prime T} D^{\prime}=-I \\
D^{\prime T} A^{\prime}-B^{\prime T} C^{\prime}=I \text { and } & D^{\prime T} B^{\prime}-B^{\prime T} D^{\prime}=0
\end{aligned}
$$

Consequently

$$
\begin{aligned}
C^{T} A-A^{T} C=0, & C^{T} B-A^{T} D=-I \\
D^{T} A-B^{T} C=I \text { and } & D^{T} B-B^{T} D=0
\end{aligned}
$$

That proves that $R_{2}$ is symplectic (see, Proposition 2.4).
By induction hypothesis there exist unitary and symplectic reflector, $\widetilde{S_{2}}$, such that $\widetilde{S_{2}} R_{2}{\widetilde{S_{2}}}^{T}=\widetilde{R_{2}}$,

Let

We take

Then $S_{2}$ is unitary and symplectic and verify $S_{2} S_{1} A S_{2}^{H} S_{1}^{H}=R$ were $R$ is symplectic and in the following form
3.1. Algorithm 3.1. Algorithm : Iterative method to compute Schur form of symplectic matrix

```
Input : \(A \in \mathbb{R}^{2 n \times 2 n}\) Symplectic, \(X_{0} \in \mathbb{R}^{2 n \times n}\)
Output: Ortho-symplectic Schur form of \(A\)
\(V=X_{0}\)
Repeat
    \(W=A V\)
    \(W=S R\) ortho-symplectic \(S R\) decomposition
    \(V=S[:, 1: n]\)
    \(R R=R[1: n, 1: n]\)
until (Convergence)
```

3.2. Numerical examples. We compared and tested the numerical results obtained by Algorithm 3.1 with Matlab eig function. Our numerical experiments were carried out with Matlab (R2009a) and run it on a Core Duo Pentium processor. The symplectic matrix $A$ is obtained from the matrix $\left(\begin{array}{c|c}M & M \\ \hline 0 & M^{-T}\end{array}\right)$ where $M=\operatorname{diag}(v)$ and by using symplectic similarity transformations randomly generated by symplectic reflectors as :

$$
A=S\left(\begin{array}{c|c}
M & M \\
\hline 0 & M^{-T}
\end{array}\right) S^{J}
$$

Example 3.1. In this example $n=20$ and $v$ is constructed as follows.
For $k=1$ to $\operatorname{fix}(n / 2)$ (Here Matlab notation is used) $v(k)=k+1$ and $v\left(\frac{n}{2}+k\right)=k^{-1}$


Example 3.2. In this example $n=10$ and $v$ is constructed as follows. For $k=1$ to $\operatorname{fix}(n / 2)$ (Here Matlab notation is used)
$v(k)=\frac{1}{k+1}$ and $v\left(\frac{n}{2}+k\right)=\left(\sqrt{\frac{k}{1000}}\right)^{-1}$


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